

B.ENG. AND M.ENG. EXAMINATIONS 2008

MATHEMATICS (INFORMATION SYSTEMS ENGINEERING E2.11)

Date Thursday 5th June 2008 2.00 - 4.00 pm

Answer FOUR questions, to include at least one from Section B.

Answers to questions from Section A and Section B should be written in different answer books.

Mathematical and statistics formulae sheets are provided.

[Before starting, please make sure that the paper is complete; there should be 7 pages, with a total of 6 questions. Ask the invigilator for a replacement if your copy is faulty.]

Section A

1. (i) A unit-amplitude square wave of width $2a$ is given by

$$u_a(t) = \begin{cases} 1, & |t| < a, \\ 0, & |t| \geq a. \end{cases}$$

Show that the Fourier transform of this function is

$$\frac{2}{\omega} \sin(\omega a)$$

where ω is the transform variable.

The functions $f(t)$, $g(t)$, $h(t)$ are related by

$$g(t) = f(t+a) - f(t-a), \quad \frac{dh}{dt} = g(t),$$

where a is a real constant.

- (ii) Find a relationship between the Fourier transforms of $h(t)$ and $f(t)$.
- (iii) Use the convolution theorem (given below) and the result of part (i) to show that

$$h(t) = \int_{-a}^a f(t-s) ds.$$

- (iv) By calculating dh/dt , check that the answer to (iii) is consistent with the definition of $g(t)$.

The Fourier convolution theorem states that

$$\hat{f}(\omega)\hat{g}(\omega) = FT \left\{ \int_{-\infty}^{\infty} f(t-s)g(s) ds \right\},$$

where FT and $\hat{\quad}$ both denote Fourier transform.

PLEASE TURN OVER

2. (i) Prove Parseval's theorem

$$\int_{-\infty}^{\infty} |f(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\widehat{f}(\omega)|^2 d\omega ,$$

relating a function $f(t)$ and its Fourier transform $\widehat{f}(\omega)$.

You may assume the result

$$\delta(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i\omega x} d\omega$$

where δ is the Dirac delta function.

- (ii) Verify Parseval's theorem for the function

$$f(t) = \begin{cases} 0, & t < 0, \\ e^{-t}, & t \geq 0. \end{cases}$$

PLEASE TURN OVER

3. A closed curve C is formed from 2 parabolae which enclose a region R . The lower of the two (C_1) has as its starting point the origin, and is formed from a section of $y = x^2$, while the upper (C_2) is part of the curve $y^2 = x$, and has its end point at the origin.

(i) Sketch the curves, marking where they intersect.

(ii) By direct evaluation, determine the value of the line integral

$$I_n = \int_{C_n} \frac{2y^4 dx - xy^3 dy}{2x^2}$$

for the cases $n = 1$ and $n = 2$.

(iii) Using Green's Theorem in the plane (given below), evaluate

$$\int_C \frac{2y^4 dx - xy^3 dy}{2x^2}.$$

(iv) Show that your answers to (ii) and (iii) are consistent.

Green's Theorem in the plane :

$$\int_C P dx + Q dy = \iint_R \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy,$$

where R is the region enclosed by the closed curve C .

PLEASE TURN OVER

4. (i) Show that the function

$$f(z) = \frac{1}{z(3z^2 + 13z + 4)}$$

has three poles.

Determine the order of each pole and calculate the residue of $f(z)$ at each pole.

- (ii) Making use of the results obtained in (i) or otherwise, determine the inverse Laplace transform of the function

$$F(s) = \frac{1}{s(3s^2 + 13s + 4)}.$$

PLEASE TURN OVER

5. A memory diagnostic test which checks the Random Access Memory (RAM) on computers is to be performed.

- (i) If there are no errors then the test always passes, but the test incorrectly passes when there are errors with probability 0.2. Two percent of computers to be tested have memory errors. If the test passes, a second, independent, extended test may be carried out. If there are no errors then the second test always passes and it incorrectly passes when there are errors with probability 0.01.

If a computer is selected at random,

- (a) find the probability that the first test detects memory errors;
- (b) find the probability that there are errors if the first test fails;
- (c) find the probability that there are errors if both tests pass.
- (ii) It is assumed that the running times of the tests follow independent normal distributions with means 5 minutes, 60 minutes and standard deviation 2 minutes, 10 minutes for the first and second tests respectively.
- (a) Find the probability that the first test takes longer than 6 minutes.
- (b) Find the probability that the first test is completed within 3 minutes.
- (c) If both tests are taken, what is the distribution of the total test time?
- (d) Running times of the first test are recorded for 10 computers giving a sample mean 5.24 minutes and sample standard deviation 2.12 minutes. Assuming that the variance is unknown, determine a 95% confidence interval for the mean running time of the first test. Does this interval support the reported mean value of 5 minutes?

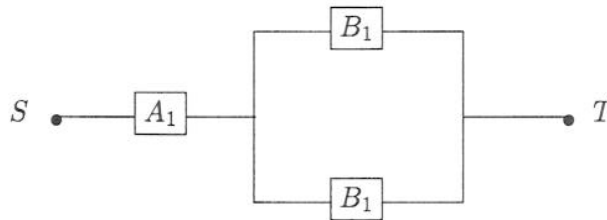
PLEASE TURN OVER

6. (i) The lifetime, T of a particular component, in hours, has probability density function

$$f(t) = \begin{cases} \lambda \beta (\lambda t)^{\beta-1} e^{-(\lambda t)^\beta} & t \geq 0 \\ 0 & t \leq 0, \end{cases}$$

with $\lambda, \beta \geq 0$.

- (a) Show that $f(t)$ is a valid probability density function.
- (b) Determine the reliability and hazard function associated with T .
- (c) Find an expression for $P(T > t_0 + t | T > t_0)$ with $t, t_0 > 0$.
- (d) For what values of λ and β is the lifetime 'memoryless'?
- (ii) A system is made up of three components: A , B_1 and B_2 . All components operate independently. A has a lifetime as described above with $\lambda = 0.5$ and $\beta = 0.8$, while B_1 and B_2 have lifetimes with $\lambda = 0.5$ and $\beta = 0.5$. The system functions as long as there is a path of functioning components between S and T .



Determine the reliability of the system at 30 minutes.

END OF PAPER

MATHEMATICAL FORMULAE

I. VECTOR ALGEBRA

$$a = a_1i + a_2j + a_3k = (a_1, a_2, a_3)$$

Scalar (dot) product: $a \cdot b = a_1b_1 + a_2b_2 + a_3b_3$

Vector (cross) product:

$$a \times b = \begin{vmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

Scalar triple product:

$$[a, b, c] = a \cdot b \times c = b \cdot c \times a = c \cdot a \times b = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

Vector triple product: $a \times (b \times c) = (c \cdot a)b - (b \cdot a)c$

2. SERIES

$$(1+x)^\alpha = 1 + \alpha x + \frac{\alpha(\alpha-1)}{2!}x^2 + \frac{\alpha(\alpha-1)(\alpha-2)}{3!}x^3 + \dots \quad (\alpha \text{ arbitrary, } |x| < 1)$$

$$e^x = 1 + x + \frac{x^2}{2!} + \dots + \frac{x^n}{n!} + \dots$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots + (-1)^n \frac{x^{2n}}{(2n)!} + \dots$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots + (-1)^n \frac{x^{2n+1}}{(2n+1)!} + \dots$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \dots + (-1)^n \frac{x^{n+1}}{(n+1)} + \dots \quad (-1 < x \leq 1)$$

3. TRIGONOMETRIC IDENTITIES AND HYPERBOLIC FUNCTIONS

$$\sin(a+b) = \sin a \cos b + \cos a \sin b;$$

$$\cos(a+b) = \cos a \cos b - \sin a \sin b.$$

$$\cos iz = \cosh z; \quad \cosh iz = \cos z; \quad \sin iz = i \sinh z; \quad \sinh iz = i \sin z.$$

4. DIFFERENTIAL CALCULUS

(a) Leibniz's formula:

$$D^n(fg) = f D^n g + \binom{n}{1} Df D^{n-1} g + \dots + \binom{n}{r} D^r f D^{n-r} g + \dots + D^n f g.$$

(b) Taylor's expansion of $f(x)$ about $x = a$:

$$f(a+h) = f(a) + hf'(a) + \frac{h^2}{2!} f''(a) + \dots + \frac{h^n}{n!} f^{(n)}(a) + \epsilon_n(h),$$

where $\epsilon_n(h) = h^{n+1} f^{(n+1)}(a + \theta h) / (n+1)!$, $0 < \theta < 1$.

(c) Taylor's expansion of $f(x, y)$ about (a, b) :

$$f(a+h, b+k) = f(a, b) + [hf_x + kf_y]_{a,b} + 1/2! [h^2 f_{xx} + 2hk f_{xy} + k^2 f_{yy}]_{a,b} + \dots$$

(d) Partial differentiation of $f(x, y)$:

i. If $y = y(x)$, then $f = F(x)$, and $\frac{dF}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \frac{dy}{dx}$.

ii. If $x = x(t)$, $y = y(t)$, then $f = F(t)$, and $\frac{dF}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$.

iii. If $x = x(u, v)$, $y = y(u, v)$, then $f = F(u, v)$, and

$$\frac{\partial F}{\partial u} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial u}, \quad \frac{\partial F}{\partial v} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial v}.$$

(e) Stationary points of $f(x, y)$ occur where $f_x = 0$, $f_y = 0$ simultaneously.

Let (a, b) be a stationary point: examine $D = [f_{xx}f_{yy} - (f_{xy})^2]_{a,b}$.

If $D > 0$ and $f_{xx}(a, b) < 0$, then (a, b) is a maximum;

If $D > 0$ and $f_{xx}(a, b) > 0$, then (a, b) is a minimum;

If $D < 0$ then (a, b) is a saddle-point.

(f) Differential equations:

i. The first order linear equation $dy/dx + P(x)y = Q(x)$ has an integrating factor $I(x) = \exp[\int P(x)dx]$, so that $\frac{d}{dx}(Iy) = IQ$.

ii. $P(x, y)dx + Q(x, y)dy = 0$ is exact if $\partial Q/\partial x = \partial P/\partial y$.

5. INTEGRAL CALCULUS

- (a) An important substitution: $\tan(\theta/2) = t$;
 $\sin \theta = 2t/(1+t^2)$, $\cos \theta = (1-t^2)/(1+t^2)$, $d\theta = 2dt/(1+t^2)$.
- (b) Some indefinite integrals:

$$\int (a^2 - x^2)^{-1/2} dx = \sin^{-1} \left(\frac{x}{a} \right), \quad |x| < a.$$

$$\int (a^2 + x^2)^{-1/2} dx = \sinh^{-1} \left(\frac{x}{a} \right) = \ln \left\{ \frac{x}{a} + \left(1 + \frac{x^2}{a^2} \right)^{1/2} \right\}.$$

$$\int (x^2 - a^2)^{-1/2} dx = \cosh^{-1} \left(\frac{x}{a} \right) = \ln \left| \frac{x}{a} + \left(\frac{x^2}{a^2} - 1 \right)^{1/2} \right|.$$

$$\int (a^2 + x^2)^{-1} dx = \left(\frac{1}{a} \right) \tan^{-1} \left(\frac{x}{a} \right).$$

6. NUMERICAL METHODS

- (a) Approximate solution of an algebraic equation:
- If a root of $f(x) = 0$ occurs near $x = a$, take $x_0 = a$ and $x_{n+1} = x_n - [f(x_n)/f'(x_n)]$, $n = 0, 1, 2, \dots$
- (Newton Raphson method).
- (b) Formulae for numerical integration: Write $x_n = x_0 + nh$, $y_n = y(x_n)$.
- Trapezium rule (1-strip): $\int_{x_0}^{x_1} y(x) dx \approx (h/2) [y_0 + y_1]$.
 - Simpson's rule (2-strip): $\int_{x_0}^{x_2} y(x) dx \approx (h/3) [y_0 + 4y_1 + y_2]$.
- (c) Richardson's extrapolation method: Let $I = \int_a^b f(x) dx$ and let I_1, I_2 be two estimates of I obtained by using Simpson's rule with intervals h and $h/2$.

Then, provided h is small enough,

$$I_2 + (I_2 - I_1)/15,$$

is a better estimate of I .

7. LAPLACE TRANSFORMS

Function	Transform	Function	Transform
$f(t)$	$F(s) = \int_0^\infty e^{-st} f(t) dt$	$af(t) + bg(t)$	$aF(s) + bG(s)$
df/dt	$sF(s) - f(0)$	$d^2 f/dt^2$	$s^2 F(s) - sf(0) - f'(0)$
$e^{at} f(t)$	$F(s-a)$	$tf(t)$	$-dF(s)/ds$
$(\partial/\partial \alpha) f(t, \alpha)$	$(\partial/\partial \alpha) F(s, \alpha)$	$\int_0^t f(t) dt$	$F(s)/s$
$\int_0^t f(u)g(t-u) du$	$F(s)G(s)$		
1	$1/s$	t^n ($n = 1, 2, \dots$)	$n!/s^{n+1}$, ($s > 0$)
e^{at}	$1/(s-a)$, ($s > a$)	$\sin \omega t$	$\omega/(s^2 + \omega^2)$, ($s > 0$)
$\cos \omega t$	$s/(s^2 + \omega^2)$, ($s > 0$)	$H(t-T) = \begin{cases} 0, & t < T \\ 1, & t > T \end{cases}$	e^{-sT}/s , ($s, T > 0$)

8. FOURIER SERIES

If $f(x)$ is periodic of period $2L$, then $f(x+2L) = f(x)$, and

$$f(x) = \frac{1}{2} a_0 + \sum_{n=1}^{\infty} a_n \cos \frac{n\pi x}{L} + \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{L}, \text{ where}$$

$$a_n = \frac{1}{L} \int_{-L}^L f(x) \cos \frac{n\pi x}{L} dx, \quad n = 0, 1, 2, \dots, \text{ and}$$

$$b_n = \frac{1}{L} \int_{-L}^L f(x) \sin \frac{n\pi x}{L} dx, \quad n = 1, 2, 3, \dots$$

Parseval's theorem

$$\frac{1}{L} \int_{-L}^L [f(x)]^2 dx = \frac{a_0^2}{2} + \sum_{n=1}^{\infty} (a_n^2 + b_n^2).$$

1. Probabilities for events

For events $A, B,$ and C	$P(A \cup B) = P(A) + P(B) - P(A \cap B)$
More generally $P(\cup A_i) =$	$\sum P(A_i) - \sum P(A_i \cap A_j) + \sum P(A_i \cap A_j \cap A_k) - \dots$
The <u>odds</u> in favour of A	$P(A) / P(\bar{A})$
<u>Conditional probability</u>	$P(A B) = \frac{P(A \cap B)}{P(B)}$ provided that $P(B) > 0$
<u>Chain rule</u>	$P(A \cap B \cap C) = P(A)P(B A)P(C A \cap B)$
<u>Bayes' rule</u>	$P(A B) = \frac{P(A)P(B A)}{P(A)P(B A) + P(\bar{A})P(B \bar{A})}$
A and B are <u>independent</u> if	$P(B A) = P(B)$
$A, B,$ and C are <u>independent</u> if	$P(A \cap B \cap C) = P(A)P(B)P(C),$ and
	$P(A \cap B) = P(A)P(B), P(B \cap C) = P(B)P(C), P(C \cap A) = P(C)P(A)$

2. Probability distribution, expectation and variance

The probability distribution for a discrete random variable X is called the probability mass function (pmf) and is the complete set of probabilities $\{p_x\} = \{P(X = x)\}$

Expectation $E(X) = \mu = \sum_x x p_x$

For function $g(x)$ of $x,$ $E\{g(X)\} = \sum_x g(x)p_x,$ so $E(X^2) = \sum_x x^2 p_x$

Sample mean $\bar{x} = \frac{1}{n} \sum_k x_k$ estimates μ from random sample x_1, x_2, \dots, x_n

Variance $\text{var}(X) = \sigma^2 = E\{(X - \mu)^2\} = E(X^2) - \mu^2$

Sample variance $s^2 = \frac{1}{n-1} \left\{ \sum_k x_k^2 - \frac{1}{n} \left(\sum_j x_j \right)^2 \right\}$ estimates σ^2

Standard deviation $\text{sd}(X) = \sigma$

If value y is observed with frequency n_y

$$n = \sum_y n_y, \quad \sum_k x_k = \sum_y y n_y, \quad \sum_k x_k^2 = \sum_y y^2 n_y$$

Skewness $\beta_1 = E\left(\frac{X - \mu}{\sigma}\right)^3$ is estimated by $\frac{1}{n-1} \sum \left(\frac{x_i - \bar{x}}{s}\right)^3$

Kurtosis $\beta_2 = E\left(\frac{X - \mu}{\sigma}\right)^4 - 3$ is estimated by $\frac{1}{n-1} \sum \left(\frac{x_i - \bar{x}}{s}\right)^4 - 3$

Sample median \bar{x} or x_{med} . Half the sample values are smaller and half larger

If the sample values x_1, \dots, x_n are ordered as $x_{(1)} \leq x_{(2)} \leq \dots \leq x_{(n)},$ then $\bar{x} = x_{(\frac{n+1}{2})}$ if n is odd, and $\bar{x} = \frac{1}{2}(x_{(\frac{n}{2})} + x_{(\frac{n+2}{2})})$ if n is even

α -quantile $Q(\alpha)$ is such that $P(X \leq Q(\alpha)) = \alpha$

Sample α -quantile $\widehat{Q}(\alpha)$ Proportion α of the data values are smaller

Lower quartile $Q1 = \widehat{Q}(0.25)$ one quarter are smaller

Upper quartile $Q3 = \widehat{Q}(0.75)$ three quarters are smaller

Sample median $\bar{x} = \widehat{Q}(0.5)$ estimates the population median $Q(0.5)$

3. Probability distribution for a continuous random variable

The cumulative distribution function (cdf) $F(x) = P(X \leq x) = \int_{x_0=-\infty}^x f(x_0)dx_0$

The probability density function (pdf) $f(x) = \frac{dF(x)}{dx}$

$E(X) = \mu = \int_{-\infty}^{\infty} x f(x)dx$, $\text{var}(X) = \sigma^2 = E(X^2) - \mu^2$, where $E(X^2) = \int_{-\infty}^{\infty} x^2 f(x)dx$

4. Discrete probability distributions

Discrete Uniform *Uniform* (n)

$$p_x = \frac{1}{n} \quad (x = 1, 2, \dots, n) \quad \mu = (n+1)/2, \quad \sigma^2 = (n^2 - 1)/12$$

Binomial distribution *Binomial* (n, θ)

$$p_x = \binom{n}{x} \theta^x (1-\theta)^{n-x} \quad (x = 0, 1, 2, \dots, n) \quad \mu = n\theta, \quad \sigma^2 = n\theta(1-\theta)$$

Poisson distribution *Poisson* (λ)

$$p_x = \frac{\lambda^x e^{-\lambda}}{x!} \quad (x = 0, 1, 2, \dots) \quad (\text{with } \lambda > 0) \quad \mu = \lambda, \quad \sigma^2 = \lambda$$

Geometric distribution *Geometric* (θ)

$$p_x = (1-\theta)^{x-1} \theta \quad (x = 1, 2, 3, \dots) \quad \mu = \frac{1}{\theta}, \quad \sigma^2 = \frac{1-\theta}{\theta^2}$$

5. Continuous probability distributions

Uniform distribution *Uniform* (α, β)

$$f(x) = \begin{cases} \frac{1}{\beta - \alpha} & (\alpha < x < \beta), \\ 0 & (\text{otherwise}). \end{cases} \quad \mu = (\alpha + \beta)/2, \quad \sigma^2 = (\beta - \alpha)^2/12$$

Exponential distribution *Exponential* (λ)

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & (0 < x < \infty), \\ 0 & (-\infty < x \leq 0). \end{cases} \quad \mu = 1/\lambda, \quad \sigma^2 = 1/\lambda^2$$

Normal distribution $N(\mu, \sigma^2)$

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right\} \quad (-\infty < x < \infty), \quad E(X) = \mu, \quad \text{var}(X) = \sigma^2$$

Standard normal distribution $N(0,1)$

If X is $N(\mu, \sigma^2)$, then $Y = \frac{X - \mu}{\sigma}$ is $N(0,1)$

6. Reliability

For a device in continuous operation with failure time random variable T having pdf $f(t)$ ($t > 0$)

The reliability function at time t $R(t) = P(T > t)$

The failure rate or hazard function $h(t) = f(t)/R(t)$

The cumulative hazard function $H(t) = \int_0^t h(t_0) dt_0 = -\ln\{R(t)\}$

The Weibull(α, β) distribution has $H(t) = \beta t^\alpha$

7. System reliability

For a system of k devices, which operate independently, let

$$R_i = P(D_i) = P(\text{"device } i \text{ operates"})$$

The system reliability, R , is the probability of a path of operating devices

A system of devices in series operates only if every device operates

$$R = P(D_1 \cap D_2 \cap \dots \cap D_k) = R_1 R_2 \dots R_k$$

A system of devices in parallel operates if any device operates

$$R = P(D_1 \cup D_2 \cup \dots \cup D_k) = 1 - (1 - R_1)(1 - R_2) \dots (1 - R_k)$$

8. Covariance and correlation

The covariance of X and Y $\text{cov}(X, Y) = E(XY) - \{E(X)\}\{E(Y)\}$

From pairs of observations $(x_1, y_1), \dots, (x_n, y_n)$ $S_{xy} = \sum_k x_k y_k - \frac{1}{n} (\sum_i x_i) (\sum_j y_j)$

$$S_{xx} = \sum_k x_k^2 - \frac{1}{n} (\sum_i x_i)^2, \quad S_{yy} = \sum_k y_k^2 - \frac{1}{n} (\sum_j y_j)^2$$

Sample covariance $s_{xy} = \frac{1}{n-1} S_{xy}$ estimates $\text{cov}(X, Y)$

Correlation coefficient $\rho = \text{corr}(X, Y) = \frac{\text{cov}(X, Y)}{\text{sd}(X) \cdot \text{sd}(Y)}$

Sample correlation coefficient $r = \frac{S_{xy}}{\sqrt{S_{xx} S_{yy}}}$ estimates ρ

9. Sums of random variables

$$E(X + Y) = E(X) + E(Y)$$

$$\text{var}(X + Y) = \text{var}(X) + \text{var}(Y) + 2 \text{cov}(X, Y)$$

$$\text{cov}(aX + bY, cX + dY) = (ac) \text{var}(X) + (bd) \text{var}(Y) + (ad + bc) \text{cov}(X, Y)$$

If X is $N(\mu_1, \sigma_1^2)$, Y is $N(\mu_2, \sigma_2^2)$, and $\text{cov}(X, Y) = c$, then $X + Y$ is $N(\mu_1 + \mu_2, \sigma_1^2 + \sigma_2^2 + 2c)$

10. Bias, standard error, mean square error

If t estimates θ (with random variable T giving t)

$$\text{Bias of } t \quad \text{bias}(t) = E(T) - \theta$$

$$\text{Standard error of } t \quad \text{se}(t) = \text{sd}(T)$$

$$\text{Mean square error of } t \quad \text{MSE}(t) = E\{(T - \theta)^2\} = \{\text{se}(t)\}^2 + \{\text{bias}(t)\}^2$$

If \bar{x} estimates μ , then $\text{bias}(\bar{x}) = 0$, $\text{se}(\bar{x}) = \sigma/\sqrt{n}$, $\text{MSE}(\bar{x}) = \sigma^2/n$, $\widehat{\text{se}}(\bar{x}) = s/\sqrt{n}$

Central limit property If n is fairly large, \bar{x} is from $N(\mu, \sigma^2/n)$ approximately

11. Likelihood

The likelihood is the joint probability as a function of the unknown parameter θ .

For a random sample x_1, x_2, \dots, x_n

$$\ell(\theta; x_1, x_2, \dots, x_n) = P(X_1 = x_1 | \theta) \cdots P(X_n = x_n | \theta) \quad (\text{discrete distribution})$$

$$\ell(\theta; x_1, x_2, \dots, x_n) = f(x_1 | \theta) f(x_2 | \theta) \cdots f(x_n | \theta) \quad (\text{continuous distribution})$$

The maximum likelihood estimator (MLE) is $\hat{\theta}$ for which the likelihood is a maximum

12. Confidence intervals

If x_1, x_2, \dots, x_n are a random sample from $N(\mu, \sigma^2)$ and σ^2 is known, then

the 95% confidence interval for μ is $(\bar{x} - 1.96 \frac{\sigma}{\sqrt{n}}, \bar{x} + 1.96 \frac{\sigma}{\sqrt{n}})$

If σ^2 is estimated, then from the Student t table for t_{n-1} we find $t_0 = t_{n-1, 0.05}$

The 95% confidence interval for μ is $(\bar{x} - t_0 \frac{s}{\sqrt{n}}, \bar{x} + t_0 \frac{s}{\sqrt{n}})$

13. Standard normal table Values of pdf $\phi(y) = f(y)$ and cdf $\Phi(y) = F(y)$

y	$\phi(y)$	$\Phi(y)$	y	$\phi(y)$	$\Phi(y)$	y	$\phi(y)$	$\Phi(y)$	y	$\Phi(y)$
0	.399	.5	.9	.266	.816	1.8	.079	.964	2.8	.997
.1	.397	.540	1.0	.242	.841	1.9	.066	.971	3.0	.999
.2	.391	.579	1.1	.218	.864	2.0	.054	.977	0.841	.8
.3	.381	.618	1.2	.194	.885	2.1	.044	.982	1.282	.9
.4	.368	.655	1.3	.171	.903	2.2	.035	.986	1.645	.95
.5	.352	.691	1.4	.150	.919	2.3	.028	.989	1.96	.975
.6	.333	.726	1.5	.130	.933	2.4	.022	.992	2.326	.99
.7	.312	.758	1.6	.111	.945	2.5	.018	.994	2.576	.995
.8	.290	.788	1.7	.094	.955	2.6	.014	.995	3.09	.999

14. Student t table Values $t_{m,p}$ of x for which $P(|X| > x) = p$, when X is t_m

m	$p=0.10$	0.05	0.02	0.01	m	$p=0.10$	0.05	0.02	0.01
1	6.31	12.71	31.82	63.66	9	1.83	2.26	2.82	3.25
2	2.92	4.30	6.96	9.92	10	1.81	2.23	2.76	3.17
3	2.35	3.18	4.54	5.84	12	1.78	2.18	2.68	3.05
4	2.13	2.78	3.75	4.60	15	1.75	2.13	2.60	2.95
5	2.02	2.57	3.36	4.03	20	1.72	2.09	2.53	2.85
6	1.94	2.45	3.14	3.71	25	1.71	2.06	2.48	2.78
7	1.89	2.36	3.00	3.50	40	1.68	2.02	2.42	2.70
8	1.86	2.31	2.90	3.36	∞	1.645	1.96	2.326	2.576

15. Chi-squared table Values $\chi_{k,p}^2$ of x for which $P(X > x) = p$, when X is χ_k^2 and $p = .995, .975, etc$

k	.995	.975	.05	.025	.01	.005	k	.995	.975	.05	.025	.01	.005
1	.000	.001	3.84	5.02	6.63	7.88	18	6.26	8.23	28.87	31.53	34.81	37.16
2	.010	.051	5.99	7.38	9.21	10.60	20	7.43	9.59	31.42	34.17	37.57	40.00
3	.072	.216	7.81	9.35	11.34	12.84	22	8.64	10.98	33.92	36.78	40.29	42.80
4	.207	.484	9.49	11.14	13.28	14.86	24	9.89	12.40	36.42	39.36	42.98	45.56
5	.412	.831	11.07	12.83	15.09	16.75	26	11.16	13.84	38.89	41.92	45.64	48.29
6	.676	1.24	12.59	14.45	16.81	18.55	28	12.46	15.31	41.34	44.46	48.28	50.99
7	.990	1.69	14.07	16.01	18.48	20.28	30	13.79	16.79	43.77	46.98	50.89	53.67
8	1.34	2.18	15.51	17.53	20.09	21.95	40	20.71	24.43	55.76	59.34	63.69	66.77
9	1.73	2.70	16.92	19.02	21.67	23.59	50	27.99	32.36	67.50	71.41	76.15	79.49
10	2.16	3.25	18.31	20.48	23.21	25.19	60	35.53	40.48	79.08	83.30	88.38	91.95
12	3.07	4.40	21.03	23.34	26.22	28.30	70	43.28	48.76	90.53	95.02	100.4	104.2
14	4.07	5.63	23.68	26.12	29.14	31.32	80	51.17	57.15	101.9	106.6	112.3	116.3
16	5.14	6.91	26.30	28.85	32.00	34.27	100	67.33	74.22	124.3	129.6	135.8	140.2

16. The chi-squared goodness-of-fit test

The frequencies n_{xy} are grouped so that the fitted frequency \hat{n}_{xy} for every group exceeds about 5.

$$\chi^2 = \sum_y \frac{(n_{xy} - \hat{n}_{xy})^2}{\hat{n}_{xy}}$$

is referred to the table of χ_k^2 with significance point p ,

where k is the number of terms summed, less one for each constraint, eg matching total frequency, and matching \bar{x} with μ

17. Joint probability distributions

Discrete distribution $\{p_{xy}\}$, where $p_{xy} = P(\{X = x\} \cap \{Y = y\})$.

Let $p_{x\bullet} = P(X = x)$, and $p_{\bullet y} = P(Y = y)$, then

$$p_{x\bullet} = \sum_y p_{xy} \quad \text{and} \quad P(X = x | Y = y) = \frac{p_{xy}}{p_{\bullet y}}$$

Continuous distribution

Joint cdf $F(x, y) = P(\{X \leq x\} \cap \{Y \leq y\}) = \int_{x_0=-\infty}^x \int_{y_0=-\infty}^y f(x_0, y_0) dx_0 dy_0$

Joint pdf $f(x, y) = \frac{d^2 F(x, y)}{dx dy}$

Marginal pdf of X $f_X(x) = \int_{-\infty}^{\infty} f(x, y_0) dy_0$

Conditional pdf of X given Y = y $f_{X|Y}(x|y) = \frac{f(x, y)}{f_Y(y)}$ (provided $f_Y(y) > 0$)

18. Linear regression

To fit the linear regression model $y = \alpha + \beta x$ by $\hat{y}_x = \hat{\alpha} + \hat{\beta}x$ from observations

$(x_1, y_1), \dots, (x_n, y_n)$, the least squares fit is $\hat{\alpha} = \bar{y} - \bar{x}\hat{\beta}$, $\hat{\beta} = \frac{S_{xy}}{S_{xx}}$

The residual sum of squares $RSS = S_{yy} - \frac{S_{xy}^2}{S_{xx}}$

$$\hat{\sigma}^2 = \frac{RSS}{n-2} \quad \frac{n-2}{\sigma^2} \hat{\sigma}^2 \text{ is from } \chi_{n-2}^2$$

$$E(\hat{\alpha}) = \alpha, \quad E(\hat{\beta}) = \beta,$$

$$\text{var}(\hat{\alpha}) = \frac{\sum x_i^2}{n S_{xx}} \sigma^2, \quad \text{var}(\hat{\beta}) = \frac{\sigma^2}{S_{xx}}, \quad \text{cov}(\hat{\alpha}, \hat{\beta}) = -\frac{\bar{x}}{S_{xx}} \sigma^2$$

$$\hat{y}_x = \hat{\alpha} + \hat{\beta}x, \quad E(\hat{y}_x) = \alpha + \beta x, \quad \text{var}(\hat{y}_x) = \left\{ \frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}} \right\} \sigma^2$$

$$\frac{\hat{\alpha} - \alpha}{\text{se}(\hat{\alpha})}, \quad \frac{\hat{\beta} - \beta}{\text{se}(\hat{\beta})}, \quad \frac{\hat{y}_x - \alpha - \beta x}{\text{se}(\hat{y}_x)}$$

are each from t_{n-2}